



## P603 LARGE ANGLE TILT SENSOR

### High-resolution tilt feedback for industrial and scientific applications

- Non-contacting inductive technology to eliminate wear
- Angle set to customer's requirement
- **Compact and self-contained**
- High durability and reliability
- High accuracy and stability
- Sealing to IP67

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek® has the expertise to supply a sensor to suit a wide variety of applications.

Our P603 is an affordable, durable, high-accuracy tilt sensor designed for industrial and scientific feedback applications. The P603, like all Positek® sensors, is supplied with the output calibrated to the angle required by the customer, between 15 and 160 degrees and with full EMC protection built The sensor provides a linear output proportional with the rotation of the sensor. There is a machined registration mark to identify the calibrated mid point.

It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important. Overall performance, repeatability and stability are outstanding over a wide temperature range. Electrical connections to the sensor are made via an industrial standard 4-pin M12 connector, with limited rotational capability to facilitate cable routing.

The sensor has a rugged stainless steel body and anodised aluminium mounting flange, the flange has two slots to simplify mounting and position adjustment. The P603 offers a range of electrical options.

Environmental sealing is to IP67.



#### **SPECIFICATION**

**Dimensions Body Diameter** 35 mm 60 mm Flange Diameter

Body Length (to seal face) 44 mm stand For full mechanical details see drawing P603-11 44 mm standard, 50 mm buffered

Independent Linearity/Hysteresis (combined error)  $<\pm 0.25^{\circ}$  - up to  $100^{\circ}$  Temperature coefficients  $<\pm 0.01\%/{\circ}$ C Gain &  $<\pm 0.01\%/{\circ}$ C Offset **Response Time** 250 mS @ 20°C typ. Resolution

Infinite 0.2 : 1 (0.6 nom. @ 25°C) < 0.02% FSO **Damping Ratio** 

Noise **Environmental Temperature Limits** 

-20°C to +85°C all output options -40°C to +125°C

Operating Storage

Sealing

**EMC Performance** EN 61000-6-2, EN 61000-6-3 IEC 68-2-6: 10 g IEC 68-2-29: 40 g Vibration Shock 350,000 hrs 40°C Gf MTRF

Drawing List

P603-11 Sensor Outline 3D models, step or .igs format, available on request

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.



# P603 LARGE ANGLE TILT SENSOR

## High-resolution tilt feedback for industrial and scientific applications

#### How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

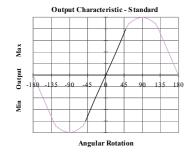
Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

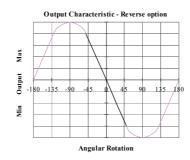
It also overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials, no requirement for separate signal conditioning.

We also offer a range of ATEX-qualified intrinsically-safe sensors.

P603		a	b	С	d
		Displacement	Output	J	Z-code

a <b>Displacement</b>		Value				
Factory set to any angle (e.g. 0-54°)	54					
b Output						
Supply V <sub>dc</sub> (tolerance)	Output	Code				
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A				
±15V nom. (±9 - 28V)	±5V	В				
+24V nom. (13 - 28V)	0.5 - 9.5V	С				
±15V nom. (±13.5 - 28V)	±10V	D				
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E				
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F				
+24V nom. (9 - 28V)	0.5 - 4.5V	G				
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	н				
Supply Current: 'A' 10mA nominal, 12mA max. 'B', 'D' & 'G' 12mA nominal, 15mA max. 'E' 26mA max. 'F' & 'H' 32mA nominal, 35mA max.						
c Connections Code						
Connector IP67 4 pin M12 IEC 61076-2-101, nylon						
Connector IP67 4 pin M12 IEC 61076-2-101, nylon, pre-wired <b>Jxx</b>						
Specify required cable length 'xx' in cm. e.g. J2000 specifies connector with 20 m of cable.						
d <b>Z-code</b> (optional)		Code				



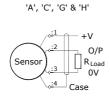


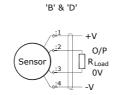


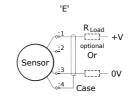
# Installation Information P603 LARGE ANGLE TILT SENSOR

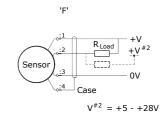
Output Option	Output Description:	Supply Voltage: V <sub>s</sub> (tolerance)	<b>Load resistance:</b> (include leads for 4 to 20mA O/Ps)
A	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	$\approx 0$ - $300\Omega$ max. @24V $\sim 1.2$ to 6V across $300\Omega$ $~\{R_L$ max. = (V_s - 18) / $20^{\cdot 3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	$\approx 0$ - $950\Omega$ max. @24V $\sim 3.8$ to 19V across $950\Omega$ $\;\;\{R_L \; max. = (V_s - 5) \; / \; 20^{\cdot 3}\}$
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	$\approx$ 0 - 300Ω max. $\sim$ 1.2 to 6V across 300Ω









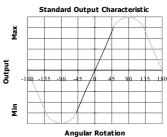


**Mechanical Mounting:** Flange mounted - see drawing P603-11. **Note:** the sensor should be mounted on a vertical face.



Direction of increasing output in calibrated sector

**Output Characteristic:** The sensor has full rotational freedom and two sectors, 180° apart, over which linear response can be achieved. At the mid point of the calibrated range the output signal will be half full scale deflection, the mounting flange will be vertical, mid point adjustment is achieved by rotating the sensor in the flange slots. In the calibrated range the output increases as the sensor is rotated in an anti-clockwise direction viewed from the flange face- see sketch above. The calibrated output is factory set to be between 15° and 160°.



**Note!** The M12 IEC connector does not rotate, the field wireable connector housing may be fitted in one of four positions for the purposes of convenient orientation of the connector and cable.

#### **Incorrect Connection Protection levels:**

**Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA.

B & D Supply leads diode protected. Output must not be taken outside  $\pm$  12V. Supply leads diode protected. Output must not be taken outside 0 to 12V.

E, F & H Protected against any misconnection within the rated voltage.